

Hence each summand in the first sum cancels with the corresponding one in the second sum and therefore  $\sum_{i=1}^n Dx_i = 0$ .  $\square$

As a concrete example take  $A$  to be the real algebra  $C^\infty(\mathbb{R}^n)$  of  $C^\infty$ -functions on  $\mathbb{R}^n$  and  $D_i = \frac{\partial}{\partial x_i}$ ,  $i \in \underline{n}$ , where  $n \geq 2$ . Then we get an  $n$ -Lie algebra on  $C^\infty(\mathbb{R}^n)$  with the product  $[g_1, \dots, g_n] := \left| \frac{\partial g_j}{\partial x_i} \right|$ .

Example 1.1 and 1.2 can also be found in Filippov [5].

**Example 1.1.3:** Let  $V$  be an  $n$ -dimensional vector space over  $K$ ,  $f$  a nonzero determinant form on  $V$  and  $0 \neq v_0 \in V$ . Then  $V$  becomes an  $n$ -Lie algebra relative to the product  $[v_1, \dots, v_n] := f(v_1, \dots, v_n) v_0$ .

In fact, by using Cramer's rule

$$f(v_1, \dots, v_n) v_0 = \sum_{i=1}^n f(v_1, \dots, v_{i-1}, v_0, v_{i+1}, \dots, v_n) v_i,$$

we get

$$\begin{aligned} & \sum_{i=1}^n [v_1, \dots, v_{i-1}, [u_1, \dots, u_{n-1}, v_i], v_{i+1}, \dots, v_n] \\ &= \sum_{i=1}^n f(u_1, \dots, u_{n-1}, v_i) [v_1, \dots, v_{i-1}, v_0, v_{i+1}, \dots, v_n] \\ &= \sum_{i=1}^n f(u_1, \dots, u_{n-1}, v_i) f(v_1, \dots, v_{i-1}, v_0, v_{i+1}, \dots, v_n) v_0 \\ &= f(u_1, \dots, u_{n-1}, \sum_{i=1}^n f(v_1, \dots, v_{i-1}, v_0, v_{i+1}, \dots, v_n) v_i) v_0 \\ &= f(u_1, \dots, u_{n-1}, f(v_1, \dots, v_n) v_0) v_0 \\ &= f(u_1, \dots, u_{n-1}, [v_1, \dots, v_n]) v_0 \\ &= [u_1, \dots, u_{n-1}, [v_1, \dots, v_n]], \end{aligned}$$

which gives the G.J.I..

**Remark 1.1.1:** Let  $V$  be an  $n$ -Lie algebra ( $n > 2$ ) with product  $[v_1, \dots, v_n]$ . For any fixed  $v_0 \in V$  we may define an  $(n-1)$ -Lie algebra structure on the underlying vector space  $V$  by  $[v_1, \dots, v_{n-1}] := [v_1, \dots, v_{n-1}, v_0]$ . Although very easy to prove, it demonstrates us how to construct an  $(n-1)$ -Lie algebra from a given  $n$ -Lie algebra.

**Definition:** Let  $V_1, V_2$  be  $n$ -Lie algebras over  $K$ . A linear map  $\tau : V_1 \rightarrow V_2$  is called