

derivations of V (see Remark 2.1), we can define (as (2.1)) a homomorphism $\gamma : \text{Der}(V) \rightarrow \text{Der}(V/\text{Rad}(V))$ with

$$\text{Ker } \gamma = \{D \in \text{Der}(V) \mid D(V) \subseteq \text{Rad}(V)\}. \quad (2.3)$$

By Theorem 2.4, $V/\text{Rad}(V)$ is semisimple. If $\text{char } K = 0$, then $\text{Der}(V/\text{Rad}(V))$ agrees with $\text{Inder}(V/\text{Rad}(V))$ and is semisimple by Theorem 2.7. But by (2.2), $\gamma(\text{Inder}(V)) = \text{Inder}(V/\text{Rad}(V))$, it follows that γ is a surjective Lie algebra homomorphism and $\text{Rad}(\text{Der}(V)) \subseteq \text{Ker } \gamma$. So we have proved

Theorem 2.9: *Let K be of characteristic 0. Let V be an n -Lie algebra over K . Let $\pi : V \rightarrow V/\text{Rad}(V)$ be the canonical homomorphism. Define a map $\gamma : \text{Der}(V) \rightarrow \text{Inder}(V/\text{Rad}(V))$ by $\gamma(D)(\pi(v)) := \pi(D(v))$. Then γ is a surjective Lie algebra homomorphism with the kernel given in (2.3). Moreover $\text{Rad}(\text{Der}(V)) \subseteq \text{Ker } \gamma$ and $\text{Rad}(\text{Der}(V))(V) \subseteq \text{Rad}(V)$.*

We now generalize the concept of reductive Lie algebras.

Definition: *An n -Lie algebra V is called reductive if $\text{Rad}(V) = C(V)$.*

Example 2.3: Let $n \geq 3$ and $V = (K^{n+1}, b, f)$ be the n -Lie algebra with the vector product. For given $x \in V$ we consider the $(n-1)$ -Lie algebra $V(x)$ on K^{n+1} with the product $[v_1, \dots, v_{n-1}]_x := [v_1, \dots, v_{n-1}, x]$ (see Remark 1.1.1). Obviously Kx is an ideal of $V(x)$ included in the centre of $V(x)$. Set $V_0 := \{v \in V \mid b(v, x) = 0\}$. Now

$$\begin{aligned} & b([V(x), \dots, V(x)]_x, x) \\ &= b([V, \dots, V, x], x) \\ &= f(V, \dots, V, x, x) = \{0\}. \end{aligned}$$

Thus $[V(x), \dots, V(x)]_x \subseteq V_0$, which implies that V_0 is an ideal of $V(x)$.

Case 1: $b(x, x) = 0$.

By the assumption $x \in V_0$. Let W be a subspace of V_0 such that the sum $V_0 = Kx + W$ is direct. Then $V_0^{(1, n-1)} = [V_0, \dots, V_0]_x = [W, \dots, W]_x$ and has dimension 1 (notice $\dim W = n-1$). Therefore V_0 is solvable. As a consequence $V(x)$ is solvable because $[V(x), \dots, V(x)]_x \subseteq V_0$.

Case 2: $b(x, x) \neq 0$.

Since $V = Kx + V_0$ (direct sum of vector spaces), the $(n-1)$ -Lie algebra $V(x)$ is the direct sum of its ideals Kx and V_0 . We show that V_0 is a simple $(n-1)$ -Lie algebra.