

Now instead of dealing with the abstract Hom(,) it is better to deal with vectors, i.e. with a concrete vector space. For this we recall the above Lemma using the so-called Mœbius trick:

Lemma Let $\epsilon \in \mathbb{R} \setminus \{0\}$. Then

$$f \mapsto \left\{ r_A^\epsilon(f) \right\}_{A \in P_0(\mathbb{R}) \setminus SL_2(\mathbb{R})}$$

$$r_A^\epsilon(f) := z \int_0^{i\infty} f(A\tau) dA\tau - \epsilon \int_0^{i\infty} f(gAg^{-1}\tau) d(gAg^{-1}\tau)$$

($g = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$, then $g \begin{pmatrix} u \\ v \end{pmatrix} g^{-1} = \begin{pmatrix} u-b \\ -c & d \end{pmatrix}$)

defines an isomorphism

$$S_2(P_0(\mathbb{R})) \xrightarrow{\sim} \mathbb{C}^{P_0(\mathbb{R}) \setminus SL_2(\mathbb{R})}$$

Proof Express $\overline{w}_f^\epsilon(B)$ ($B \in P_0(\mathbb{R})$) in terms of the $r_A^\epsilon(f)$.

Write $B_j = \pm T^{n_1} S T^{n_2} S \dots T^{n_r} S$

($T = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$, $S = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$;
recall $SL_2(\mathbb{R}) = \langle S, T \rangle$)

Set

$$B_j = \pm T^{n_1} \dots T^{n_r} S, \quad B_0 = 1$$

Then

$$\int_0^{B_0} = \int_0^{B_{1,0}} + \int_{B_{1,0}}^{B_{2,0}} + \dots + \int_{B_{r-1,0}}^{B_{r,0}}$$

then

$$\int_0^{B_0} f(\tau) d\tau = \int_0^{B_{1,0}} f(\tau) d\tau + \int_{B_{1,0}}^{B_{2,0}} f(\overline{B}_1 \tau) d(\overline{B}_1 \tau) + \dots + \int_0^{B_{r-1,0}} f(\overline{B}_{r-1} \tau) d\overline{B}_{r-1} \tau$$

Note that $\overline{B}_{j-1} B_{j,0} = T^{n_j} S \theta = T^{n_j} i\infty = i\infty$.

Do same with gBg , etc.

$$\overline{w}_f^\epsilon(B) = r_{B_0}^\epsilon(f) + r_{B_1}^\epsilon(f) + \dots + r_{B_{r-1}}^\epsilon(f). \quad \square$$